Reg. No. :

## $Question \ Paper \ Code: X \ 60512$

B.E./B.Tech. DEGREE EXAMINATIONS, NOVEMBER/DECEMBER 2020 Seventh Semester Electrical and Electronics Engineering EE 2403/EE 73/10133EEE25 – SPECIAL ELECTRICAL MACHINES (Regulations 2008/2010) (Common to PTEE 2403/10133EEE25 – Special Electrical Machines for B.E. (Part-Time) Sixth/Seventh semester – EEE – Regulations 2009/2010)

Time : Three Hours

Maximum : 100 Marks

Answer ALL questions

## PART - A

(10×2=20 Marks)

- 1. List the types of synchronous reluctance motors.
- 2. Give the difference between synchronous reluctance motor and switched reluctance motor.
- 3. Name the various modes of excitation in stepping motor.
- 4. Define the terms holding and detente torques as referred to stepper motor.
- 5. Write the voltage and torque equations of a switched reluctance motor.
- 6. List the methods of rotor position sensing in switched reluctance motor.
- 7. Classify the types of BLDC motor.
- 8. How the demagnetization occurs in PMBLDC motor ?
- 9. Write torque and EMF equation of PM synchronous motor.
- 10. Write the significance of power controllers of permanent magnet synchronous motors.

|     |   | PART – B                              | (5×16=80 Marks)                                      |
|-----|---|---------------------------------------|--|
| 11. | a) Derive the voltage and torqu<br>draw the phasor diagram and    | e equations of s<br>l explain the cha | ynchronous reluctance motors,<br>aracteristics. (16) |
|     | (OR)  |                                       |  |
|     | b) Explain the working of variab reluctance motor.                | le reluctance typ                     | pe and hybrid type synchronous (16)                  |
| 12. | a) Explain the construction oper<br>Also explain about micro step | ation of variable<br>ping.            | e reluctance type stepper motor.<br>(16)             |
|     | (OR)  |                                       |  |
|     | b) i) Derive the reluctance torqu                                 | ue of a stepper r                     | notor. (8)   |
|     | ii) Calculate the stepping ang type stepper motor.                | le for a 3 phase                      | 24 pole permanent magnet (8)                         |
| 13. | a) Explain with neat diagrams th switched reluctance motors.      | ne constructiona                      | l details and operation of rotary                    |
|     | (OR)  |                                       |  |
|     | b) i) Explain with neat circuit a for the control of switched     | ny two configura<br>reluctance moto   | ations of power converters used<br>or. (12)          |
|     | ii) State the advantages of set                                   | nsorless operati                      | on. <b>(4)</b>                                       |
| 14. | a) Discuss the hysteresis type co<br>diagram.                     | ırrent regulatio                      | n of PMBLDC motor with neat<br>(16)                  |
|     | (OR)  |                                       |  |
|     | b) Analyze the operation of elect diagram.                        | ronic commutate                       | or in PMBLDC motor with neat                         |
| 15. | a) Write short notes on :   |                                       |  |
|     | i) Volt-ampere requirements                                       | in PMSM Moto                          | r. <b>(8)</b>  |
|     | ii) Torque/speed characteristi                                    | cs in PMSM Mo                         | otor. (8)  |
|     | (OR)  |                                       |  |

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b) Derive EMF and torque equations of permanent magnet synchronous motor.